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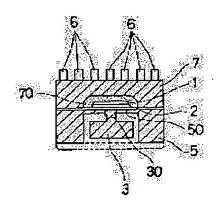
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# (54) ACCELERATION SENSOR

# (57)Abstract:

PURPOSE: To axial obtain a low-cost sensor which can detect acceleration in three directions by a method wherein, when a weight is moved with reference to a substrate mounting plate, the substrate mounting plate and a single-crystal structure are deformed integrally and the electric resistance of a detection element is changed.

CONSTITUTION: A single-crystal substrate 1 is constituted of a square silicon chip, and it is provided with a detection element whose electric resistance is changed by mechanical deformation. A substrate mounting plate 2 is formed to be square shape which is a little larger than the substrate 1. A base stand 5 is formed to be a rectangular shape in a plane view, it is provided with a central thin sheetlike part 50, and a weight 3 is installed via a shaft part 30. Then, when an acceleration sensor constituted in this manner is attached to an object to be measured and an acceleration motion is caused, the weight 3 is moved



with reference to the mounting plate 2 due to inertia, the mounting plate 2 and the substrate 1 are deformed integrally due to its movement, and the resistance value of the detection element is changed. A change in the resistance value of the detection element is converted into a voltage by an electronic device, and the acceleration of the object to be measured is read out as a voltage value.

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# **CLAIMS**

# [Claim(s)]

[Claim 1] While having the sensing element (R) from which electric resistance changes with mechanical deformations on the straight line (Y) which intersects perpendicularly with a straight—line (X) top and this, said sensing element (R) centers on the intersection C of a straight line (X) and (Y). A same number individual every The single crystal substrate distributed and arranged (1), The substrate tie-down plate with which it has the coefficient of thermal expansion near the coefficient of thermal expansion of this single crystal substrate (1), and the field side, on the other hand, consisted of that metal plate used as the root face of a single crystal substrate (1) (2), The weight which fixed through the thin shank to a part for the another side surface part of said intersection (C) and a corresponding substrate tie-down plate (2) (3), The electronic instrument made to change resistance change of the above-mentioned sensing element (R) into electrical-potential-difference change is provided. The acceleration sensor characterized by a substrate tie-down plate (2) and a single crystal substrate (1) deforming in one, and making it the electric resistance of each sensing element (R) have changed when weight (3) moves to a substrate tie-down plate (2).

[Claim 2] While having the sensing element (R) from which electric resistance changes with mechanical deformations on the straight line (Y) which intersects perpendicularly with a straightline (X) top and this, said sensing element (R) centers on the intersection C of a straight line (X) and (Y). A same number individual every The single crystal substrate distributed and arranged (1), The substrate tie-down plate with which it has the coefficient of thermal expansion near the coefficient of thermal expansion of this single crystal substrate (1), and the field side, on the other hand, consisted of that metal plate used as the root face of a single crystal substrate (1) (2), The pedestal with the central sheet metal-like section (50) which has fixed to the another side side side of said substrate tie-down plate (2) (5), The weight formed in said intersection (C) and the corresponding central sheet metal-like section (50) through the thin shaft (3). The electronic instrument made to change resistance change of the above-mentioned sensing element (R) into electrical-potential-difference change is provided. The acceleration sensor characterized by a substrate tie-down plate (2) and a single crystal substrate (1) deforming in one with said central sheet metal-like section (50), and making it the electric resistance of each sensing element (R) have changed when weight (3) moves to the central sheet metal-like section (50).

[Claim 3] The acceleration sensor according to claim 1 or 2 characterized by equipping a straight line (X) and (Y) with four sensing elements (R), respectively.

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# **DETAILED DESCRIPTION**

[Detailed Description of the Invention]

[0001]

[Industrial Application] This invention relates to an acceleration sensor.

[0002]

[Description of the Prior Art] There is a thing as shown in <u>drawing 16</u> or <u>drawing 17</u> as an acceleration sensor. Etching processing (Sign E shows the etching processing section) of the silicon substrate is carried out, and the two thin film sections are made to constitute, and he makes [ this thin film part ] a part for the weight section 91 and the both ends of a copper plate into the frame section 92 for said between [ the thin film sections ] part with a variant part 90, and is trying to surround said weight section 91 and variant part 90 with the silicon caps 93 and 93 by this sensor, as shown in this drawing.

[0003] The sensing element (usually called a piezoresistive element) from which electric resistance changes with mechanical deformations, respectively is prepared in the connection part with the frame section 92 in said variant part 90, a variant part 92 carries out elastic deformation with change of the relative-position relation between the frame section 92 and the weight section 91, and it is made for resistance of said sensing element to have changed. In addition, the electronic circuitry which changes resistance change of a sensing element into electrical-potential-difference change is made to provide in this acceleration sensor. [0004] Therefore, when this acceleration sensor is attached in a device under test and accelerated motion is carried out, the relative-position relation between the weight section 91 and the frame section 92 will change with inertia, and the resistance of a sensing element will change, consequently the acceleration of a device under test can be read with an electrical-potential-difference value. However, in the above-mentioned acceleration sensor, there is a problem that only configuration top 1 shaft orientations (for example, the direction of X of the X-Y-Z directions) can be measured.

[0005] Moreover, by this sensor, in the process which forms a variant part 90, since a deep and exact etching technique is needed, it also has the problem of becoming cost quantity.
[0006]

[Problem(s) to be Solved by the Invention] So, let it be a technical problem to offer the acceleration sensor which can detect the acceleration of the triaxial direction and can be manufactured by low cost in this invention.

[0007]

[Means for Solving the Problem] While this acceleration sensor is equipped with the sensing element R from which electric resistance changes with mechanical deformations on the straight line Y which intersects perpendicularly with a straight-line X top and this, said sensing element R centers on the intersection C of straight-line X-Y. A same number individual every The single crystal substrate 1 distributed and arranged, The substrate tie-down plate 2 with which it has the coefficient of thermal expansion near the coefficient of thermal expansion of this single crystal substrate 1, and the field side, on the other hand, consisted of that metal plate used as the root face of the single crystal substrate 1, Said intersection C and the weight 3 which fixed through the thin shank to a part for the another side surface part of the corresponding substrate

tie-down plate 2, When the electronic instrument made to change resistance change of the above-mentioned sensing element R into electrical-potential-difference change is provided and weight 3 moves to the substrate tie-down plate 2, the substrate tie-down plate 2 and the single crystal substrate 1 deform in one, and it is made for the electric resistance of each sensing element R to have changed.

[0008] While this acceleration sensor is equipped with the sensing element R from which electric resistance changes with mechanical deformations on the straight line Y which intersects perpendicularly with a straight-line X top and this, said sensing element R centers on the intersection C of straight-line X and Y. A same number individual every Moreover, the single crystal substrate 1 distributed and arranged, The substrate tie-down plate 2 with which it has the coefficient of thermal expansion near the coefficient of thermal expansion of this single crystal substrate 1, and the field side, on the other hand, consisted of that metal plate used as the root face of the single crystal substrate 1, The pedestal 5 with the central sheet metal-like section 50 which has fixed to the another side side of said substrate tie-down plate 2, Said intersection C and the weight 3 formed in the corresponding central sheet metal-like section 50 through the thin shaft, When the electronic instrument made to change resistance change of the above-mentioned sensing element R into electrical-potential-difference change is provided and weight 3 moves to the central sheet metal-like section 50, the substrate tie-down plate 2 and the single crystal substrate 1 deform in one with said central sheet metal-like section 50, and it is made for the electric resistance of each sensing element R to have changed. [0009]

[Function] This invention acts as follows. When the acceleration sensor of this invention is attached in a device under test and accelerated motion is carried out, weight 3 moves to the substrate tie-down plate 2 according to inertia, the substrate tie-down plate 2 and the single crystal substrate 1 deform in one in connection with this, and the resistance of a sensing element R changes. Resistance change of this sensing element R will be changed into an electrical potential difference by the electronic instrument, and the acceleration of a device under test can read it as an electrical-potential-difference value.

[0010] Here, since it has the sensing element R from which electric resistance changes with mechanical deformations to the above-mentioned single crystal substrate 1 on the straight line Y which intersects perpendicularly with a straight-line X top and this, and said sensing element R is distributed a same number individual every centering on the intersection C of straight-line X-Y and it arranges, the acceleration of the triaxial direction of X-Y-Z can detect. Moreover, by this sensor, since an advanced etching technique which was indicated in the column of a Prior art becomes unnecessary, it can be manufactured by low cost.

[0011] In addition, since coefficient of thermal expansion of the above-mentioned substrate tiedown plate 2 is made into the coefficient of thermal expansion near the single crystal substrate 1, although a variant part consists of two structures, a big resistance change of the sensing element R by change of ambient temperature does not take place like the sensor indicated in the column of a Prior art. Moreover, when weight 3 moves to the central sheet metal-like section 50 of the pedestal 5 installed by the substrate tie-down plate 2 to the central sheet metal-like section 50 in the case of what has weight 3, the substrate tie-down plate 2 and the single crystal substrate 1 deform in one with the central sheet metal-like section 50. [0012]

[Example] Hereafter, it explains according to the drawing in which the configuration of this invention was shown as an example. The acceleration sensor of this example is what surrounds the sensor section with a pedestal 5 and cap 7, as shown in <u>drawing 1</u>. Fundamentally The substrate tie-down plate 2 which fixed on the top face of the central sheet metal-like section 50 of the pedestal 5 with the central sheet metal-like section 50, and this pedestal 5 as shown in <u>drawing 2</u> or <u>drawing 6</u>, The lead 6 of a large number arranged in the perimeter of said substrate tie-down plate 2, the single crystal substrate 1 which fixed on said substrate tie-down plate 2, said single crystal substrate 1, and lead 6 part on a pedestal 5 consist of wrap caps 7. [0013] As shown in <u>drawing 3</u> or <u>drawing 4</u>, the silicon chip of a square configuration constitutes the single crystal substrate 1, and it is equipped with the sensing element R from which electric

resistance changes with mechanical deformations on the straight line Y which intersects perpendicularly with a straight-line X top and this. In addition, it has carried out electrical installation (wire bonding) of these and the lead 6 with Wire W while distributing every two of said sensing element R and arranging it centering on the intersection C of straight-line X-Y, as shown in this drawing or drawing 6.

[0014] The substrate tie-down plate 2 consists of covar, 42 alloys, etc., and as shown in <u>drawing 6</u>, it is formed in the shape of [ than the single crystal substrate 1 / somewhat larger ] a square. The pedestal 5 is formed in the shape of a plane view rectangle, as shown in <u>drawing 1</u> or <u>drawing 2</u>, and it is arranging weight 3 in the intersection C in this central sheet metal-like section 50, and a corresponding part through a shank 30 while it has the above-mentioned central sheet metal-like section 50. In addition, the so-called mold resin for IC constitutes the pedestal 5 whole containing weight 3 from this example.

[0015] As shown in drawing 1 or drawing 6, from the substrate tie-down plate 2, only fixed distance is detached, and lead 6 arranges inner one end, and has bent the outer edge side. The cap 7 is formed in the shape of a plane view rectangle, and is constituted by synthetic resin homogeneous as a pedestal 5. Moreover, an electronic instrument has the bridge circuit 4 which connects and changes, as the above-mentioned sensing element R is shown in drawing 5, and it enables it to have read in resistance change of said sensing element R the acceleration which acts on this sensor as an electrical signal while it changes the resistance of each sensing element R into an electrical-potential-difference value.

[0016] Since this sensor is considered as the above-mentioned configuration, as shown below, it can perform measurement of acceleration.

\*\* Weight 3 moves [ as opposed to / when this acceleration sensor is attached in the acceleration device under test of X component and the left-hand side of the direction of X is made to carry out accelerated motion, as it is shown in <a href="mailto:drawing 7">drawing 7</a> / a pedestal 5 ] to right-hand side according to inertia, and deform in connection with this in [ the substrate tie-down plate 2 and the single crystal substrate 1 / as the central sheet metal / of a pedestal 5 /-like section 50 ] one. And the electric resistance of a sensing element R changes in connection with this (resistance increases the sensing elements Rx1 and Rx3 on which distortion of the direction of tension acts, and, as for the sensing element Rx2 on which distortion of the compression direction acts, and Rx4, resistance decreases).

[0017] In addition, when the right-hand side of the direction of X is made to carry out accelerated motion of the device under test, the resistance of sensing elements Rx2 and Rx4 increases, and a sensing element Rx1 and the resistance of Rx3 decrease.

\*\* The resistance of a sensing element R changes in the mode as the above-mentioned \*\* with the same acceleration of Y component of the acceleration device under test of Y component. \*\* Weight 3 moves [ as opposed to / when this acceleration sensor is attached in the acceleration device under test of Z component and accelerated motion is carried out to the Z direction bottom, as it is shown in drawing 8 / a pedestal 5 ] to the bottom according to inertia, and deform into convex in connection with this in [ the substrate tie-down plate 2 and the single crystal substrate 1 / as the central sheet metal / of a pedestal 5 /-like section 50 ] one. Therefore, sensing elements Rx1 and Rx3 The resistance of Rx2 and Rx4 increases. In addition, when accelerated motion of the device under test is carried out to the Z direction bottom, they are sensing elements Rx1 and Rx3. The resistance of Rx2 and Rx4 decreases.

[0018] Thus, the resistance of a sensing element R is detected as electrical-potential-difference

change by the electronic instrument which includes the bridge circuit 4 which changes with migration directions of a sensor, respectively, and which described this resistance change above although it changes, and it is indicated by vision as acceleration of each X-Y-Z direction. Here, the manufacture approach of the sensor of this example is explained below.

The leadframe LF which consists of the connection S which connects said substrate tie-down plate 2 and both lead 6 with two or more substrate tie-down plates 2 with which the single crystal substrate 1 as shows the 1st \*\* first to drawing 9 from the metal plates (covar, 42 alloys, etc.) near the coefficient of thermal expansion of the single crystal substrate 1 is stretched, and the lead 6 of a large number arranged in order to surround these, respectively is manufactured.

The 2nd process, next the single crystal substrate 1 which made the sensing element R arrange like the above are stretched to each substrate tie-down plate 2, as shown in <u>drawing 10</u> or <u>drawing 11</u>, and between lead 6 is electrically connected with a sensing element with Wire W proper.

As shown in the 3rd process, then <u>drawing 12</u>, the surface-protection material 70 is applied and cap 7 is cast by the mold resin for IC that the prepuce of this surface-protection material 70 grade should be carried out (molding).

As shown in the 4th process and <u>drawing 13</u>, a pedestal 5 is cast by the mold resin for IC (molding).

[0019] In addition, it may be made to perform molding in this process to it of the 3rd process, and coincidence.

it is shown in <u>drawing 14</u> after that [5th process] — as — Leadframe LF to the connection S — separation (a two-dot chain line n is cut) — carrying out — the outer edge part of lead 6 — bending (foaming being carried out) — an acceleration sensor is completed.

[0020] In addition, the tubed pedestal 5 without the central sheet metal-like section 50 may be made to constitute, the metal weight 3 may be welded to the inferior-surface-of-tongue parts of the intersection C of straight-line X-Y, and the corresponding substrate tie-down plate 2 through a shaft 30, and, thereby, a sensor may be made to constitute, as it changes to the above-mentioned example and is shown in <u>drawing 15</u>. Moreover, it changes to the above-mentioned example and you may make it form a pedestal 5 in the shape of a cap, as shown in <u>drawing 15</u>.

[0021]

[Effect of the Invention] Since this invention is the above configurations, it has the following effectiveness. The acceleration sensor which can detect the acceleration of the triaxial direction and can be manufactured by low cost from the contents indicated from the column of an operation has been offered.

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### DESCRIPTION OF DRAWINGS

[Brief Description of the Drawings]

[Drawing 1] The appearance perspective view of the acceleration sensor of the example of this invention.

[Drawing 2] The sectional view of said acceleration sensor.

[Drawing 3] The top view showing arrangement of the sensing element which the single crystal substrate of said acceleration sensor was made to possess.

[Drawing 4] The sectional view of the important section of said acceleration sensor.

[Drawing 5] Drawing of a bridge circuit which changes into an electrical-potential-difference value the resistance of the sensing element which said acceleration sensor was made to possess.

[Drawing 6] The top view showing relation, such as a wire, with the substrate tie-down plate which said acceleration sensor was made to possess, a single crystal substrate, and a lead.
[Drawing 7] The sectional view showing deformation conditions, such as a single crystal substrate at the time of acting the acceleration of the direction of X on said acceleration sensor.

[Drawing 8] The sectional view showing deformation conditions, such as a single crystal substrate at the time of acting the acceleration of a Z direction on said acceleration sensor. [Drawing 9] The top view of the leadframe used for manufacture of said acceleration sensor. [Drawing 10] The top view showing the condition of having carried out wire bonding of between leads to the single crystal substrate while fixing the single crystal substrate on the top face of the substrate tie-down plate of said leadframe.

[Drawing 11] The side elevation showing the condition of having fixed the single crystal substrate on the top face of the substrate tie-down plate of said leadframe.

[Drawing 12] The sectional view showing the condition of having prepared in the leadframe the cap which applies surface-protection material to said single crystal substrate etc., and carries out the prepuce of these.

[Drawing 13] The sectional view showing the condition of having prepared the pedestal in said leadframe.

[Drawing 14] The top view having shown the isolation location of the connection in said leadframe.

[Drawing 15] The sectional view of the acceleration sensor of other examples of this invention.

Drawing 16] The sectional view of the conventional acceleration sensor.

[Drawing 17] The important section perspective view of the conventional acceleration sensor.

[Description of Notations]

R Sensing element

X Straight line

Y Straight line

C Intersection

- 1 Single Crystal Substrate
- 2 Substrate Tie-down Plate
- 3 Weight

4 Bridge Circuit 5 Pedestal 50 Central Sheet Metal-like Section

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(54)【発明の名称】加速度センサー

# (57)【要約】

【目的】 三軸方向の加速度が検出でき且つ低コストで 製造できる加速度センサーを提供すること。

【構成】 機械的変形により電気抵抗が変化する検出素子Rを直線X上及びこれと直交する直線Y上に備えるして共に前記検出素子Rが直線X・Yの交点Cを中心として同数個づつ振り分けて配置してある単結晶基板1と、この単結晶基板1の熱膨張率に近い熱膨率を有し、そので連結晶基板1の固着面となる金属板で構成2と、前記交点Cと対応する基板取付板2と、前記交点Cと対応する基板取付板2と大方面部分に細い軸部を介して固着された変換せる。上記検出素子Rの抵抗変化を電圧変化に変換せる。と、上記検出素子Rの抵抗変化で変換してある。

【特許請求の範囲】

【請求項1】 機械的変形により電気抵抗が変化する検 出索子(R)を直線(X)上及びこれと直交する直線 (Y)上に備えると共に前記検出素子(R)が直線 (X) (Y) の交点Cを中心として同数個づつ振り分け て配置してある単結晶基板 (1) と、この単結晶基板 (1) の熱膨張率に近い熱膨張率を有し、その一方面側 が単結晶基板 (1) の固着面となる金属板で構成された 基板取付板(2)と、前記交点(C)と対応する基板取 付板(2)の他方面部分に細い軸部を介して固着された 10 重り(3)と、上記検出素子(R)の抵抗変化を電圧変 化に変換せしめる電子装置とを具備し、基板取付板 (2) に対して重り(3) が移動したときには基板取付 板(2)と単結晶基板(1)とが一体的に変形して各検 出案子(R)の電気抵抗が変化するようにしてあること を特徴とする加速度センサー.

【請求項2】 機械的変形により電気抵抗が変化する検 出素子(R)を直線(X)上及びこれと直交する直線 (Y)上に備えると共に前記検出素子(R)が直線 (X) (Y)の交点Cを中心として同数個づつ振り分け 20 て配置してある単結晶基板 (1) と、この単結晶基板 (1) の熱膨張率に近い熱膨張率を有し、その一方面側 が単結晶基板(1)の固着面となる金属板で構成された 基板取付板(2)と、前記基板取付板(2)の他方面側 に固着されている、中央薄板状部(50)を有した基台 (5) と、前記交点(C)と対応する中央薄板状部(5) 0) に細い軸を介して設けられている重り(3)と、上 記検出素子(R)の抵抗変化を電圧変化に変換せしめる 電子装置とを具備し、中央薄板状部 (50) に対して重 り(3)が移動したときには基板取付板(2)と単結晶 基板(1)が前記中央薄板状部(50)と一体的に変形 して各検出素子(R)の電気抵抗が変化するようにして あることを特徴とする加速度センサー.

【請求項3】 直線 (X) (Y) にそれぞれ四個の検出 素子 (R) を備えていることを特徴とする請求項1又は 2記載の加速度センサー。

【発明の詳細な説明】

[0001]

【産業上の利用分野】この発明は、加速度センサーに関するものである。

[0002]

【従来の技術】加速度センサーとしては図16や図17に示すようなものがある。このセンサーでは、同図に示すように、シリコン基板をエッチング処理(エッチング処理部を符号Eで示す)して二つの薄膜部を構成させ、この薄膜部分を変形部90と、前記薄膜部相互間部分を重り部91と、銅板の両端部分をフレーム部92とし、前記重り部91や変形部90をシリコンキャップ93、93で包囲するようにしている。

【0003】前記変形部90におけるフレーム部92と 50

の接続部分には、それぞれ機械的変形により電気抵抗が変化する検出素子(通常、ピエゾ抵抗素子と呼ばれる)を設けてあり、フレーム部92と重り部91との相対位置関係の変化に伴って変形部92が弾性変形し、前記検出素子の抵抗が変化するようにしてある。尚、この加速度センサーでは、検出素子の抵抗変化を電圧変化に変換する電子回路を具備させてある。

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【0004】したがって、被測定物にこの加速度センサーを取付けて加速度運動をさせた場合、慣性により重り部91とフレーム部92との相対位置関係が変化して検出素子の抵抗値が変化し、その結果、被測定物の加速度を電圧値で読み取れることとなる。しかしながら、上記加速度センサーでは、その構成上一軸方向(例えば、X-Y-Z方向のうちのX方向)しか測定できないという問題がある。

【0005】又、このセンサーでは、変形部90を形成する工程において、深く且つ正確なエッチング技術を必要とするから、コスト高となってしまうという問題も有している。

[0006]

【発明が解決しようとする課題】そこで、この発明では、三軸方向の加速度が検出でき且つ低コストで製造できる加速度センサーを提供することを課題とする。

[0007]

【課題を解決するための手段】この加速度センサーは、機械的変形により電気抵抗が変化する検出素子Rを直線 X上及びこれと直交する直線 Y上に備えると共に前記検出素子Rが直線 X・Yの交点 Cを中心として同数個である単結晶基板 1 の無態張率を有し、その一方面側が単結晶基板 1 のの間をなる金属板で構成を2 と、前記交点 Cと対応する基板取付板 2 と、前記交点 Cと対応する基板取付板 2 のに設定して重り 3 が移動したを具備し、基板取付板 2 に対して重り 3 が移動したときには基板取付板 2 と単結晶基板 1 とが一体的に変形した検出素子Rの電気抵抗が変化するようにしてある。

【0008】また、この加速度センサーは、機械的変形により電気抵抗が変化する検出素子Rを直線X上及びびれた直交する直線Y上に備えると共に前記検出素子分別では、変点Cを中心として同数個活動を表別ででは、この単結晶基板1のの単結晶基板1と、この単結晶と、の一方面側が単結晶と、その一方面側が単結晶と、の固着面となる金属板で構成された基板取付板2の他方面側に固着されてと対応を有した基份で構成に固着では、前記を取付板2の他方面側に固着では、下すの影響を介したと対応で変換である電子装置とを具備し、中央板状部50に細い軸を介して設けられてで変換で、上記検出素子Rの抵抗変化を電圧変化に変換である電子装置とを具備し、中央板状部50に対して重りる電子装置とを具備し、中央板状部50に対して重りるが移動したときには基板取付板2と単結晶基板1が前

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記中央薄板状部50と一体的に変形して各検出素子Rの 電気抵抗が変化するようにしてある。

#### [0009]

【作用】この発明は次のように作用する。 被測定物にこ の発明の加速度センサーを取付けて加速度運動をさせた 場合、慣性により重り3が基板取付板2に対して移動 し、これに伴って基板取付板2と単結晶基板1とが一体 的に変形して検出素子Rの抵抗値が変化する。この検出 素子Rの抵抗変化は電子装置により電圧に変換され、被 測定物の加速度が電圧値として読み取れることとなる。 【0010】ここで、上記単結晶基板1には、機械的変 形により電気抵抗が変化する検出素子Rを直線X上及び これと直交する直線Y上に備えてあり、前記検出素子R は直線X・Yの交点Cを中心として同数個づつ振り分け て配置してあることから、X-Y-Zの三軸方向の加速 度が検出し得る。また、このセンサーでは、従来の技術 の欄に記載したような高度なエッチング技術は不要とな るから低コストで製造できる。

【0011】尚、上記基板取付板2の熱膨張率は単結晶 基板1に近い熱膨張率としてあるから、変形部が二つの 構成物から成るものであるにもかかわらず、従来の技術 の欄に記載したセンサーと同様に雰囲気温度の変化によ る検出素子Rの大きな抵抗変化は起こらない。また、基 板取付板2に添着された基台5の中央薄板状部50に重 り3を有するものの場合、中央薄板状部50に対して重 り3が移動したときには基板取付板2及び単結晶基板1 が中央薄板状部50と一体的に変形する。

# [0012]

【実施例】以下、この発明の構成を実施例として示した 図面に従って説明する。この実施例の加速度センサー は、図1に示すように、基台5とキャップ7によりセン サー部を包囲するものであり、基本的には、図2や図6 に示すように、中央薄板状部50を有した基台5と、こ の基台5の中央薄板状部50の上面に固着された基板取 付板2と、前記基板取付板2の周囲に配設された多数の リード6と、前記基板取付板2上に固着された単結晶基 板1と、前記単結晶基板1及び基台5上のリード6部分 を覆うキャップ7とから構成されている。

【0013】単結晶基板1は、図3や図4に示すよう に、正方形状のシリコンチップにより構成してあり、機 40 械的変形により電気抵抗が変化する検出素子Rを直線※ 上及びこれと直交する直線Y上に備えている。尚、前記 検出素子Rは、同図や図6に示す如く直線X・Yの交点 Cを中心として二個づつ振り分けて配置させてある。と共 に、これらとリード6とをワイヤーWで電気的接続(ワ イヤーポンディング) してある。

【0014】基板取付板2は、コパールや42アロイ等 から構成されており、図6に示すように単結晶基板1よ りも少し大きい正方形状に形成されている。基台5は、

り、上記した中央薄板状部50を有すると共にこの中央 薄板状部50における交点Cと対応する部分に軸部30 を介して重り3を配設している。尚、この実施例では、 重り3を含む基台5全体を所謂IC用モールド樹脂で構 成している。

【0015】リード6は、図1や図6に示すように、内 端側を基板取付板2から一定距離だけ離して配置し、外 端側を折り曲げてある。キャップ7は、平面視長方形状 に形成されており基台5と同質の合成樹脂により構成さ れている。また、電子装置は、上記検出案子Rを図5に 示す如く接続して成るブリッジ回路4を有するもので、 各検出素子Rの抵抗値を電圧値に変換すると共に前記検 出素子Rの抵抗変化からこのセンサーに作用する加速度 を電気信号として読み取れるようにしてある。

【0016】このセンサーは上記構成としてあるから以 下に示す如く加速度の測定ができる。

### OX成分の加速度

被測定物にこの加速度センサーを取付けてX方向の左側 に加速度運動をさせた場合、図7に示すように慣性によ り重り3が基台5に対して右側に移動し、これに伴って 基板取付板2及び単結晶基板1が基台5の中央薄板状部 50と一体的に変形する。そして、これに伴い検出素子 Rの電気抵抗が変化(引張り方向の歪みが作用する検出 素子R.,, R., は抵抗値が増加し、圧縮方向の歪みが作 用する検出素子R... R.,は抵抗値が減少する)する。 【0017】尚、被測定物をX方向の右側に加速度運動 させた場合、検出素子R.,, R.,の抵抗値が増加し、検 出素子R.i. R.iの抵抗値が減少する。

# Ø Y成分の加速度

3.0 被測定物のY成分の加速度は上記□と同様の態様で検出 素子Rの抵抗値が変化する。

#### ③ Z 成分の加速度

被測定物にこの加速度センサーを取付けて2方向の下側 に加速度運動をさせた場合、図8に示すように慣性によ り重り3が基台5に対して上側に移動し、これに伴って 基板取付板2及び単結晶基板1が基台5の中央薄板状部 50と一体的に凸状に変形する。したがって検出素子R ... R.: . R.: R.: の抵抗値は増加する。尚、被測 定物を2方向の上側に加速度運動させた場合、検出素子 R.,, R., , R.,, R.,の抵抗値は減少する。

【0018】このように、検出素子Rの抵抗値はセンサ 一の移動方向によりそれぞれ異なる変化するが、この抵 抗変化は上記したブリッジ回路4を含む電子装置により 電圧変化として検出され、各X-Y-Z方向の加速度と して視覚表示される。ここで、以下に、この実施例のセ ンサーの製造方法について説明する。

# 第1工程

先ず、単結晶基板1の熱膨張率に近い金属板 (コバー ル、42アロイ等)から、図9に示すような、単結晶基 図1や図2に示すように平面視長方形状に形成されてお 50 板1が張設される複数の基板取付板2と、これらをそれ

ぞれ取り囲むべく配列された多数のリード6と、前記基 板取付板2とリード6相互を繋ぐ接続部Sから成るリー ドフレームLFを製作する.

#### 第2工程

次に、検出素子Rを上記の如く配列させた単結晶基板 1 を、図10や図11に示すように、各基板取付板2に張 設し、検出素子とリード 6 相互間を適正にワイヤーWで 電気的に接続する.

### 第3工程

続いて、図12に示すように、表面保護材70を塗布 し、この表面保護材70等を包皮すべくIC用モールド 樹脂でキャップ?を成型(モールディング)する。

そして、図13に示すように、IC用モールド樹脂で基 台5を成型(モールディング)する。

【0019】尚、この工程におけるモールディングは第 3工程のそれと同時に行うようにしてもよい。

#### 第5工程

その後、図14に示すように、リードフレームLFから 端部分を折曲げる(フォーミングする)と、加速度セン サーは完成する。

【0020】尚、上記実施例にかえて、図15に示すよ うに、中央薄板状部50が無い筒状の基台5を構成さ せ、直線X・Yの交点Cと対応する基板取付板2の下面 部分に金属製の重り3を軸30を介して溶接し、これに よりセンサーを構成させてもよい。又、上記実施例にか えて、図15に示すように基台5をキャップ状に形成す るようにしてもよい.

### [0021]

【発明の効果】この発明は上記の様な構成であるから次 の効果を有する。作用の欄から記載した内容から、三軸 方向の加速度が検出でき且つ低コストで製造できる加速 度センサーを提供できた。

# 【図面の簡単な説明】

【図1】この発明の実施例の加速度センサーの外観斜視

【図2】前記加速度センサーの断面図。

【図3】前記加速度センサーの単結晶基板に具備させた 検出素子の配置を示す平面図。

【図4】 前記加速度センサーの要部の断面図。

【図6】前記加速度センサーに具備させた基板取付板

抗値を電圧値に変換するブリッジ回路の図。

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【図5】前記加速度センサーに具備させた検出素子の抵

と、単結晶基板と、リードと、ワイヤー等の関係を示す 平面図。

【図7】前記加速度センサーにX方向の加速度が作用し た場合における、単結晶基板等の変形状態を示す断面

【図8】前記加速度センサーにZ方向の加速度が作用し 10 た場合における、単結晶基板等の変形状態を示す断面

【図9】前記加速度センサーの製作に使用されるリード フレームの平面図.

【図10】前記リードフレームの基板取付板の上面に単 結晶基板を固着すると共に単結晶基板とリード相互間を ワイヤーボンディングした状態を示す平面図。

【図11】前記リードフレームの基板取付板の上面に単 結晶基板を固着した状態を示す側面図。

【図12】前記単結晶基板等に表面保護材を塗布し、こ 接続部Sを分離(二点鎖線nを切断)し、リード6の外 20 れらを包皮するキャップをリードフレームに設けた状態 を示す断面図。

> 【図13】前記リードフレームに基台を設けた状態を示 す断面図。

> 【図14】前記リードフレームにおける接続部の切離し 位置を示した平面図。

> 【図15】この発明の他の実施例の加速度センサーの断 面図。

【図16】従来の加速度センサーの断面図。

【図17】従来の加速度センサーの要部斜視図。

30 【符号の説明】

> R 検出素子

X 直線

直線

点交

単結晶基板

2 基板取付板

重り

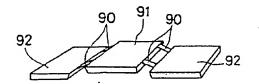
ブリッジ回路

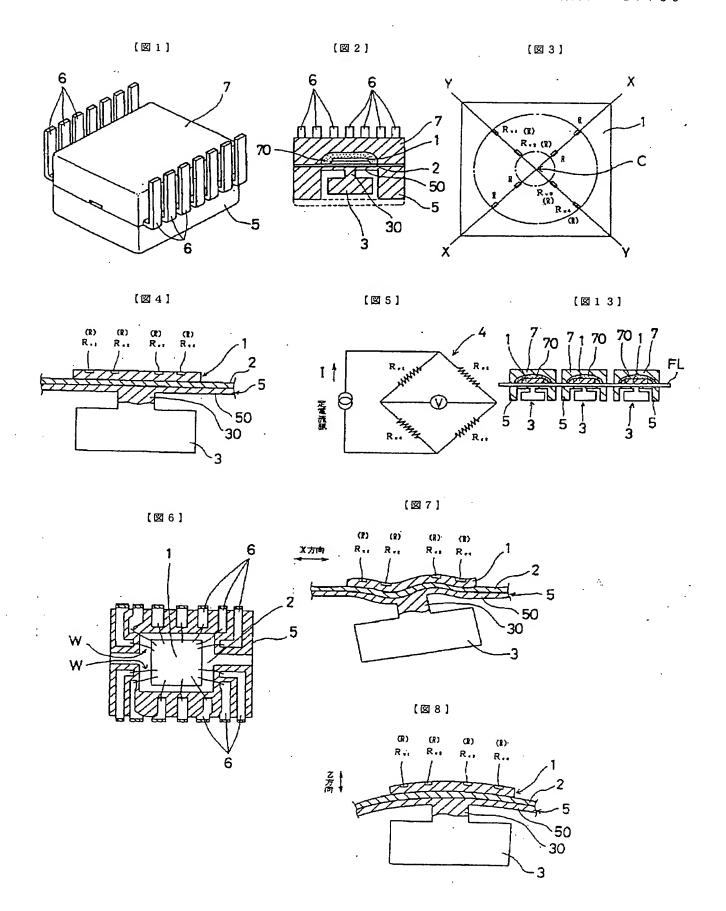
基台

40 5 0 中央薄板状部

【図12】

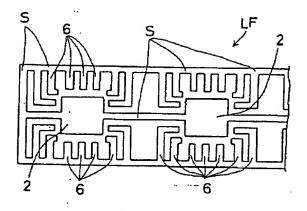
[図17]

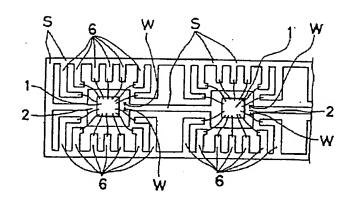




【図9】

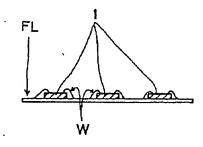


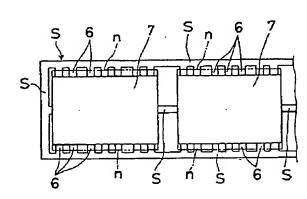




(図11]

【図14】





【図15】

【図16】

